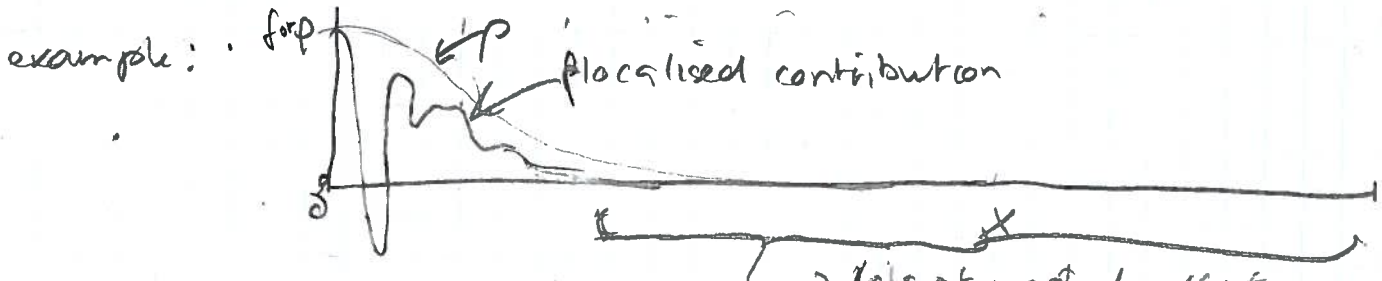


high d  $\Rightarrow$  MC more efficient compared to grid



suppose we know another function  $p(x)$ , which we can integrate, and which is somewhat similar and  $> 0$  if  $f \neq 0$

$$\int dx f(x) = \int dx p(x) \frac{f(x)}{p(x)}$$

average this instead of  $f$ .

draw  $p$ -distributed point instead of homogeneous points concentrate where  $f$  is large

error in  $\langle f \rangle$

$$\int = \langle f/p \rangle_p$$

$$\text{error}^2 = (\langle f^2 \rangle - \langle f \rangle^2) \frac{1}{N}$$

$$= \left[ \frac{1}{N} \sum_i f(x_i)^2 - \left( \frac{1}{N} \sum_i f(x_i) \right)^2 \right] \frac{1}{N}$$

big fluctuations in  $f$

or error in  $\langle f/p \rangle_p$

$$\text{error}^2 = \left( \langle \left( \frac{f}{p} \right)^2 \rangle_p - \langle \frac{f}{p} \rangle_p^2 \right) \frac{1}{N}$$

not so big fluctuations in  $f/p$

$$= \left[ \frac{1}{N} \sum_i \left( \frac{f(x_i)}{p(x_i)} \right)^2 - \left( \frac{1}{N} \sum_i \frac{f(x_i)}{p(x_i)} \right)^2 \right] \frac{1}{N}$$

Key is to pick good  $p$

- analytically manageable
- easy to draw from

drawing gaussian random variables

draw  $X_1, X_2$  between 0, 1

$$R = 2\pi X_1$$

$$R = [-\log(X_2)]^{1/2}$$

$R$  gets  $X \exp(-x^2)$  type dist

$$Y_1 = R \cos \phi$$

$$Y_2 = R \sin \phi$$

$$p_R(R) dR = \int p(x) dx = \left[ \frac{1}{(-\log(x_2))^{1/2}} \frac{1}{x_2} \right]^{-1} \propto R \exp(-R^2)$$

14x45 mm

calculating some average:

$$\langle A \rangle = \frac{\sum_{\text{states } \alpha} A(\alpha) \exp(-\beta E(\alpha))}{\sum_{\alpha} \exp(-\beta E(\alpha))} = Z$$

$$\frac{\int_{\text{phase space}} d\gamma A(\gamma) \exp(-\beta E(\gamma))}{\int d\gamma \exp(-\beta E(\gamma))}$$

example: Ising model  
 Hopfield & Supriya has discussed this system just in 2d

$$H = -J \sum_{nn} s_i s_j - K \sum_i s_i$$

$\uparrow$  coupling       $\uparrow$  field  
 direction

every spin is just up or down  
 $\Rightarrow$  should be simple enough



in 3d, 5x5x5 grid (not big)

$$N = 125 \quad \# \text{ states } 2^{125} = 10^{37}$$

calc 2 or something  
 0.1 GHz computer =  $10^9$  calcs/second.

$\Rightarrow O(10^{28} \text{ s}) \approx O(10^{20} \text{ years}) \gg$  lifetime of universe.

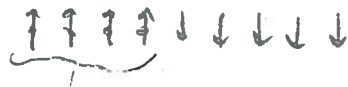
considering all states is hopeless

MC says just some random subset instead  $a_i$

$$\langle A \rangle = \frac{\frac{1}{B} \sum_{i=1}^B A(\alpha_i) \exp(-\beta E(\alpha_i))}{\frac{1}{B} \sum_{i=1}^B \exp(-\beta E(\alpha_i))} \rightarrow \frac{\langle A \exp(-\beta E) \rangle_{\text{set}}}{\langle \exp(-\beta E) \rangle_{\text{set}}}$$

Now consider low T. --- spins tend to align

most random states do not look like this.



to get sensible convergence, we need these states to be sampled

$O(1)$  out of  $10^{37}$ . ... B must be very large

same trick as with MC integration: importance sampling  
 solution: bias the random states  $p(\alpha)$  density

$$\langle A \rangle = \frac{1}{B} \sum_{i=1}^B \xi(\alpha_i) \quad \text{with } p(\alpha) = \frac{A(\alpha) \exp(-\beta E)}{Z}$$

same story about errors:  $(\langle \xi^2 \rangle - \langle \xi \rangle^2)$   
 smaller than  $(\langle A^2 \rangle - \langle A \rangle^2)$

good choice would be  $p(\alpha) \propto \exp(-\beta E(\alpha))$

IMPORTANCE SAMPLING

Markov-chain MC

all about obtaining sampling of  $\exp(-\beta E)$

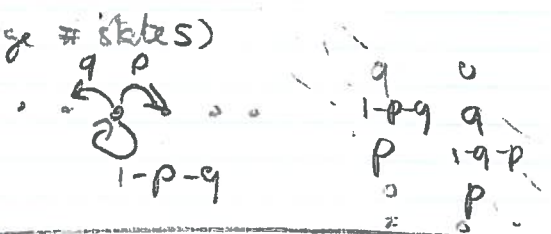
Markov chain { set of n states  $\alpha_1 \dots \alpha_N$   
transfer probs between states  $P_{ij}$

- no memory (depends only on previous state)
- used to model lots of processes; examples

- 1. simplistic attempt at modeling weather precipitation (in a day)

yes no  
yes  $\begin{pmatrix} 1-p & p \\ q & 1-q \end{pmatrix}$   
no

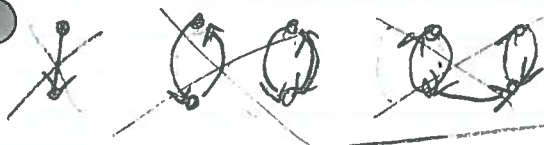
- random walk on a line (large # states)  
state = where walker is
- NS model



Idea of metropolis type algorithms is to construct a Markov chain that moves the system to likely configurations (with the correct eq. dist)

- end up in the correct equilibrium
- accessibility: must be possible to reach all states (detailed)
- balance: there has to be an equilibrium in the Markov chain.

- accessibility



- balance

equilibrium: state  $\alpha_i$ ; population  $a_i$

$P_{ij} a_j = a_i$ ; eigenvalue equation for  $(a_1, \dots, a_n)$  (eigenvalue 1)

example ①

$P = \begin{pmatrix} 1/3 & 1/3 \\ 2/3 & 2/3 \end{pmatrix} \Rightarrow a = \frac{1}{3}(1, 2)$

example ②  $\frac{1}{2} \rightleftarrows \frac{1}{4} \rightleftarrows \frac{1}{2}$   
 $\Rightarrow a = (\frac{1}{4}, \frac{1}{2}, \frac{1}{4})$